

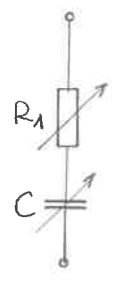
8. AC-Technik (Frequenzverhalten) – Teil 2

- 8.1) Geg.:
- a1) $C = 250 \text{ pF}$; $f = 50 \text{ kHz}$; $R_1 = 10 \text{ k}\Omega, 50 \text{ k}\Omega, 100 \text{ k}\Omega$;
 - a2) $R_1 = 50 \text{ k}\Omega$; $f = 50 \text{ kHz}$; $C = 50 \text{ pF}, 100 \text{ pF}, 250 \text{ pF}$;
 - a3) $R_1 = 50 \text{ k}\Omega$; $C = 250 \text{ pF}$; $f = 10 \text{ kHz}, 20 \text{ kHz}, 50 \text{ kHz}$;

Aes.: Z - Ortskurven

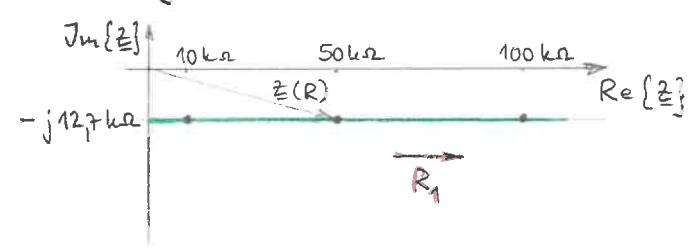
Lös.: a) $Z = R_1 + X_c = R_1 + \frac{1}{j\omega C} = R_1 - j \frac{1}{\omega C}$;

Maßstab: $10 \text{ k}\Omega \hat{=} 0,5 \text{ cm}$



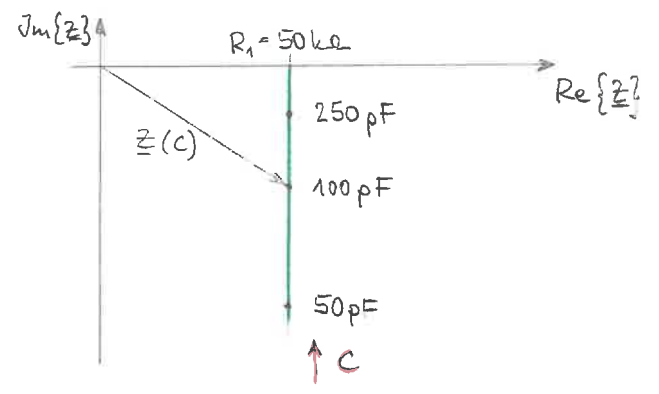
a1) $Z(R)$ - Ortskurve: $\text{Im}\{Z\} = \text{const.}$

R_1	$-\text{Im}\{Z\}$
10 kΩ	12,73 kΩ
50 kΩ	12,73 kΩ
100 kΩ	12,73 kΩ



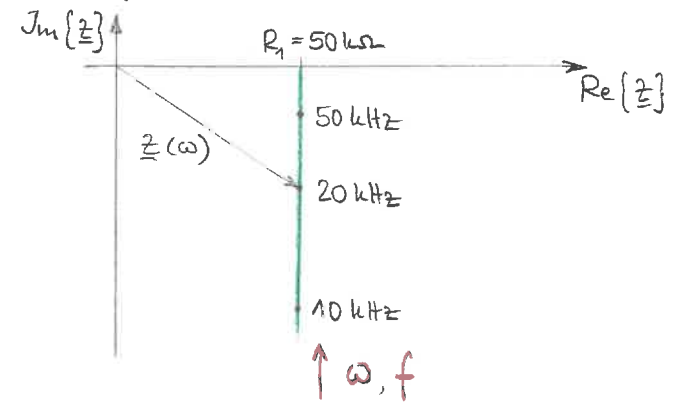
a2) $Z(C)$ - Ortskurve: $\text{Re}\{Z\} = \text{const.} = R_1$

C	$-\text{Im}\{Z\}$
50 pF	63,66 kΩ
100 pF	31,83 kΩ
250 pF	12,73 kΩ



a3) $Z(\omega)$ - Ortskurve: $\text{Re}\{Z\} = \text{const.} = R_1$

f	ω	$-\text{Im}\{Z\}$
10 kHz	$62,8 \cdot 10^3 \frac{1}{s}$	63,66 kΩ
20 kHz	$125,7 \cdot 10^3 \frac{1}{s}$	31,83 kΩ
50 kHz	$314,1 \cdot 10^3 \frac{1}{s}$	12,73 kΩ



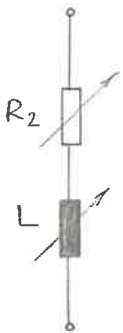
8. AC-Technik (Frequenzverhalten) - Teil 2

- 8.1) Geg.: b1) $L = 10 \text{ mH}$; $f = 50 \text{ kHz}$; $R_2 = 1 \text{ k}\Omega, 5 \text{ k}\Omega, 10 \text{ k}\Omega$;
 b2) $R_2 = 5 \text{ k}\Omega$; $f = 50 \text{ kHz}$; $L = 1 \text{ mH}, 5 \text{ mH}, 10 \text{ mH}$;
 b3) $R_2 = 5 \text{ k}\Omega$; $L = 10 \text{ mH}$; $f = 5 \text{ kHz}, 25 \text{ kHz}, 50 \text{ kHz}$;

Ges.: Z -Ortskurven

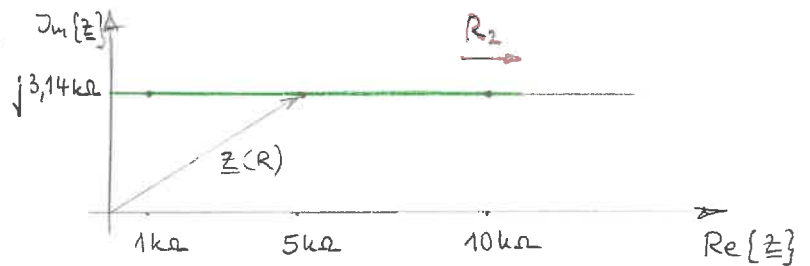
Lös.: b) $Z = R_2 + X_L = R_2 + j\omega L$;

Maßstab: $1 \text{ k}\Omega \hat{=} 0,5 \text{ cm}$



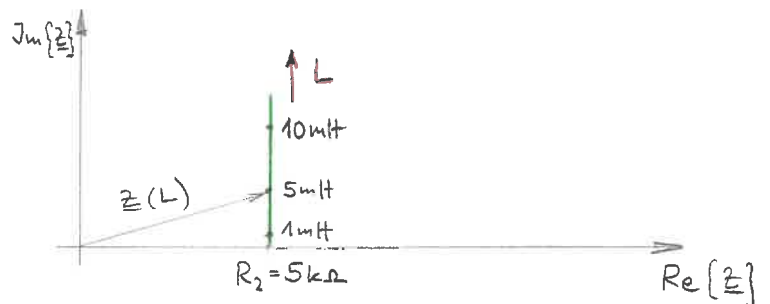
b1) $Z(R)$ -Ortskurve: $\text{Im}\{Z\} = \text{const.}$

R_2	$+ \text{Im}\{Z\}$
1 kΩ	3,14 kΩ
5 kΩ	3,14 kΩ
10 kΩ	3,14 kΩ



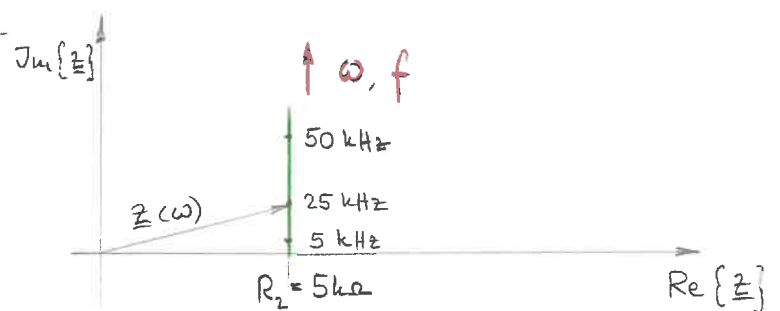
b2) $Z(L)$ -Ortskurve: $\text{Re}\{Z\} = \text{const.} = R_2$

L	$+ \text{Im}\{Z\}$
1 mH	314 Ω
5 mH	1.570 Ω
10 mH	3.140 Ω



b3) $Z(\omega)$ -Ortskurve: $\text{Re}\{Z\} = \text{const.} = R_2$

f	ω	$+ \text{Im}\{Z\}$
5 kHz	$31,4 \cdot 10^3 \frac{1}{s}$	314 Ω
25 kHz	$157 \cdot 10^3 \frac{1}{s}$	1.570 Ω
50 kHz	$314 \cdot 10^3 \frac{1}{s}$	3.140 Ω



8. AC-Technik (Frequenzverhalten) - Teil 2

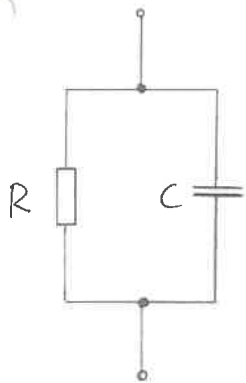
8.2) Geg.: $R = 1 \text{ k}\Omega$, $C = 10 \text{ }\mu\text{F}$; $f = 10 \text{ kHz}$, 20 kHz , 50 kHz ;

- Ges.:
- $Y(\omega)$ -Ortskurve, Grenzfrequenz f_g berechnen u. einzeichnen
 - $Z(\omega)$ -Ortskurve

Lös.:

$$Y = G + B_C = \frac{1}{R} + \frac{1}{X_C} = \frac{1}{R} + j\omega C$$

\uparrow $\text{Re}\{Y\}$ \uparrow $\text{Im}\{Y\}$



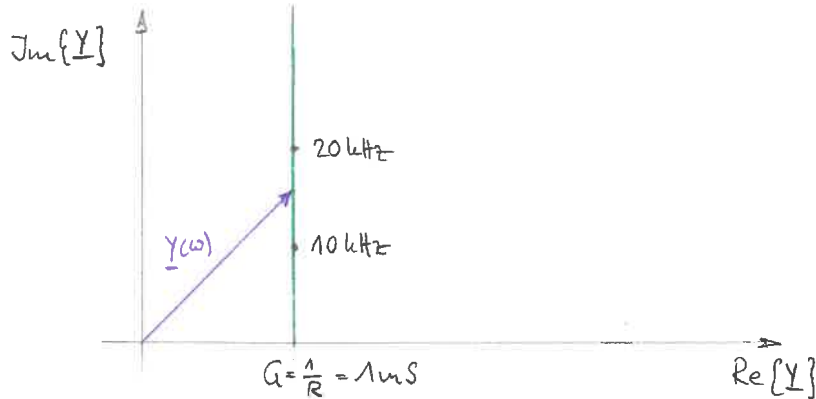
f	ω	$G = \frac{1}{R}$	$+ \text{Im}\{Y\}$
10 kHz	$62,8 \cdot 10^3 \frac{1}{s}$	1 mS	0,63 mS
20 kHz	$125,7 \cdot 10^3 \frac{1}{s}$	1 mS	1,26 mS
50 kHz	$314,1 \cdot 10^3 \frac{1}{s}$	1 mS	3,14 mS

Grenzfrequenz f_g :
 (bei Phasenwinkel $\varphi = 45^\circ$)
 $\Rightarrow |\text{Re}\{Y\}| = |\text{Im}\{Y\}|$

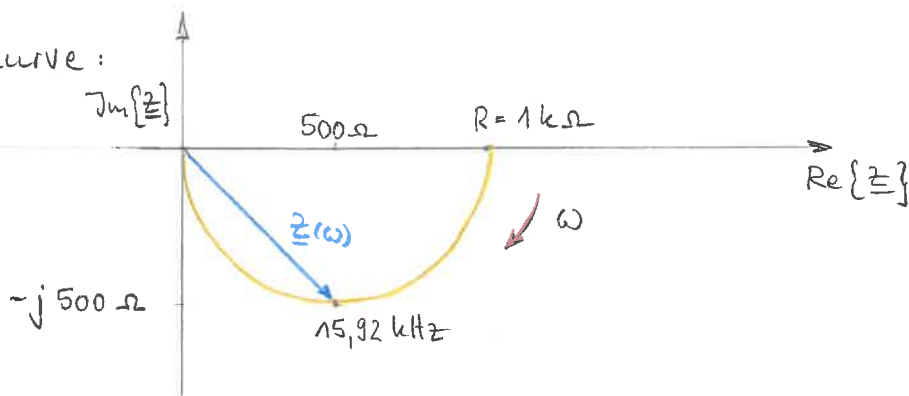
$$1 \text{ mS} = 2\pi \cdot f \cdot C$$

$$f_g = \frac{1 \cdot 10^{-3} \frac{A}{V}}{2 \cdot \pi \cdot 10 \cdot 10^{-6} \frac{A}{V_s}} = 15,92 \text{ kHz}$$

$Y(\omega)$ -Ortskurve: Maßstab: $1 \text{ mS} \stackrel{\wedge}{=} 2 \text{ cm}$



$Z(\omega)$ -Ortskurve:



8. AC-Technik (Frequenzverhalten) - Teil 2

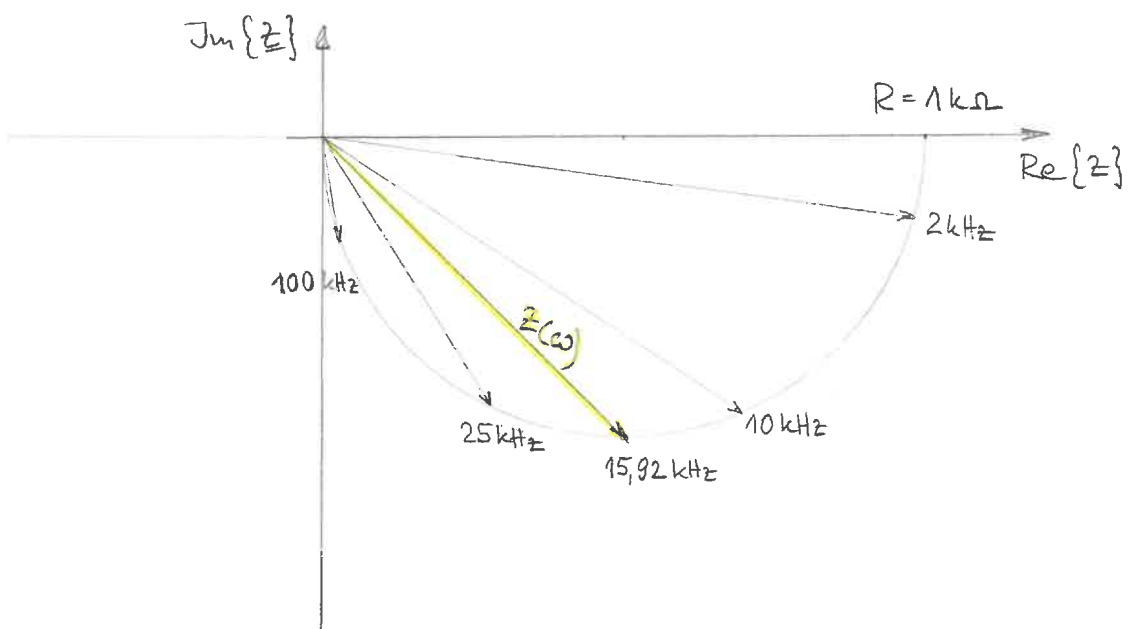
zu Aufg. 8.2

Frequenz f	R	Xc	Z	Phasenwinkel φ	Re{Z}	Im{Z}	Z	Zeigerlänge von Z
0,05 kHz	1 kΩ	318,310 kΩ	1,000 kΩ	-0,18°	999,990 Ω	-3,142 Ω	999,995 Ω	4,000 cm
1 kHz	1 kΩ	15,915 kΩ	0,998 kΩ	-3,60°	996,068 Ω	-62,585 Ω	998,032 Ω	3,992 cm
2 kHz	1 kΩ	7,958 kΩ	0,992 kΩ	-7,16°	984,454 Ω	-123,710 Ω	992,197 Ω	3,969 cm
5 kHz	1 kΩ	3,183 kΩ	0,954 kΩ	-17,44°	910,170 Ω	-285,938 Ω	954,028 Ω	3,816 cm
10 kHz	1 kΩ	1,592 kΩ	0,847 kΩ	-32,14°	716,957 Ω	-450,477 Ω	846,733 Ω	3,387 cm
15 kHz	1 kΩ	1,061 kΩ	0,728 kΩ	-43,30°	529,587 Ω	-499,124 Ω	727,727 Ω	2,911 cm
16 kHz	1 kΩ	1,000 kΩ	0,707 kΩ	-45,00°	500,000 Ω	-500,000 Ω	707,107 Ω	2,828 cm
20 kHz	1 kΩ	0,796 kΩ	0,623 kΩ	-51,49°	387,727 Ω	-487,232 Ω	622,677 Ω	2,491 cm
25 kHz	1 kΩ	0,637 kΩ	0,537 kΩ	-57,52°	288,400 Ω	-453,018 Ω	537,029 Ω	2,148 cm
50 kHz	1 kΩ	0,318 kΩ	0,303 kΩ	-72,34°	92,000 Ω	-289,025 Ω	303,314 Ω	1,213 cm
100 kHz	1 kΩ	0,159 kΩ	0,157 kΩ	-80,96°	24,705 Ω	-155,223 Ω	157,177 Ω	0,629 cm
200 kHz	1 kΩ	0,080 kΩ	0,079 kΩ	-85,45°	6,293 Ω	-79,077 Ω	79,327 Ω	0,317 cm
500 kHz	1 kΩ	0,032 kΩ	0,032 kΩ	-88,18°	1,012 Ω	-31,799 Ω	31,815 Ω	0,127 cm
1.000 kHz	1 kΩ	0,016 kΩ	0,016 kΩ	-89,09°	0,253 Ω	-15,911 Ω	15,913 Ω	0,064 cm
10.000 kHz	1 kΩ	0,002 kΩ	0,002 kΩ	-89,91°	0,003 Ω	-1,592 Ω	1,592 Ω	0,006 cm
100.000 kHz	1 kΩ	0,000 kΩ	0,000 kΩ	-89,99°	0,000 Ω	-0,159 Ω	0,159 Ω	0,001 cm

$$Y = \sqrt{G^2 + B_c^2}$$

$$\left(\frac{1}{Z}\right)^2 = \left(\frac{1}{R}\right)^2 + \left(\frac{1}{X_c}\right)^2 \quad \leadsto \quad Z = \sqrt{\frac{1}{\left(\frac{1}{R}\right)^2 + (2\pi f \cdot C)^2}} ;$$

$$\varphi = \arctan \frac{X_c}{R} - 90^\circ ;$$

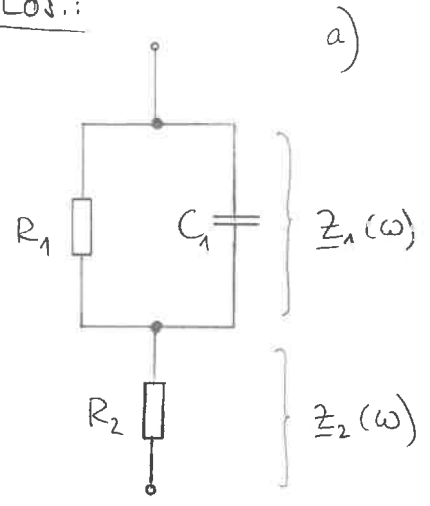


8. AC-Technik (Frequenzverhalten) - Teil 2

8.3) Geg.: Reihenschaltung von $R_1 \parallel C_1$ mit Z_2 ; $Z_2 = R_2$;

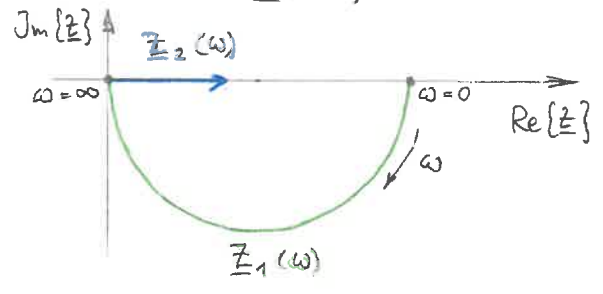
Ges.: prinzip. Verlauf der $Z(\omega)$ -Ortskurve u.
Diskussion der Frequenzpunkte $\omega = 0$ u. $\omega = \infty$;

Lös.:



a) Der konstante komplexe Widerstand $Z_2(\omega)$ ist hier ein reeller Widerstand R_2 , dessen Ortskurve $Z_2(\omega)$ als eine Gerade in der reellen Achse liegt.
Die $Z_1(\omega)$ -Ortskurve der $R_1 \parallel C_1$ -Schaltung hat die Form eines Halbkreises im 4. Quadranten und den Durchmesser R_1 .
⇒ Durch Verschiebung der $Z_1(\omega)$ -Ortskurve um R_2 ergibt sich die resultierende $Z(\omega)$ -Ortskurve

Einzelortskurven $Z_1(\omega)$ u. $Z_2(\omega)$:



b) Betrachtung der Frequenzpunkte $\omega = 0$ u. $\omega = \infty$:

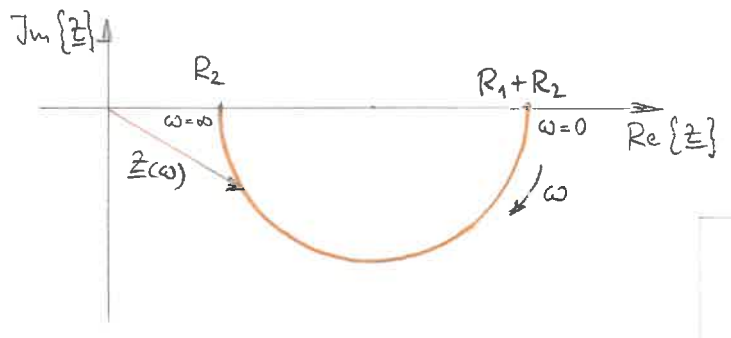
$$Y_1 = \frac{1}{R_1} + j\omega C_1$$

$$\leadsto Z_1 = \frac{1}{\frac{1}{R_1} + j\omega C_1} = \frac{R_1}{1 + j\omega R_1 C_1}$$

u. $Z_2 = R_2$

$$\leadsto Z = Z_1 + Z_2 = R_2 + \frac{R_1}{1 + j\omega R_1 C_1}$$

Resultierende $Z(\omega)$ -Ortskurve:



$$\omega = 0 : Z(\omega) = R_2 + \frac{R_1}{1+0} = R_1 + R_2$$

$$\omega = \infty : Z(\omega) = R_2 + 0 = R_2$$

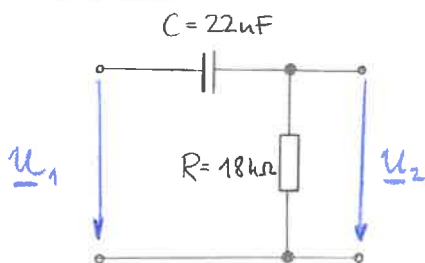
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8.4) Geg.: RC-Hochpass; $f_n = 10 \text{ Hz}, 100 \text{ Hz}, 400 \text{ Hz}, 1 \text{ kHz}, 10 \text{ kHz}$;
 $R = 18 \text{ k}\Omega$ u. $C = 22 \text{ nF}$

Ges.: Amplituden- u. Phasegang für die Frequenzen f_n

Lös.:



$$\frac{U_2}{U_1} = \frac{R}{R + \frac{1}{j\omega C}} = \frac{1}{1 - j \frac{1}{\omega RC}}$$

$$\frac{U_2}{U_1} = \frac{1}{\sqrt{1 + \left(\frac{1}{\omega RC}\right)^2}}$$

-3 dB - Grenzfrequenz:

$$\omega_g = \frac{1}{R \cdot C} \Rightarrow f_g = \frac{1}{2\pi R \cdot C}$$

normierte Frequenz:

$$\Omega = \frac{\omega}{\omega_g} = \frac{\omega}{\frac{1}{RC}} = \omega RC$$

$$\begin{aligned} \omega_g &= \frac{1}{RC} = \\ &= \frac{1}{18 \cdot 10^3 \frac{\text{V}}{\text{A}} \cdot 22 \cdot 10^{-9} \frac{\text{As}}{\text{V}}} \\ &= 2.525,25 \frac{1}{\text{s}}; \\ &(f_g = 401,9 \text{ Hz}) \end{aligned}$$

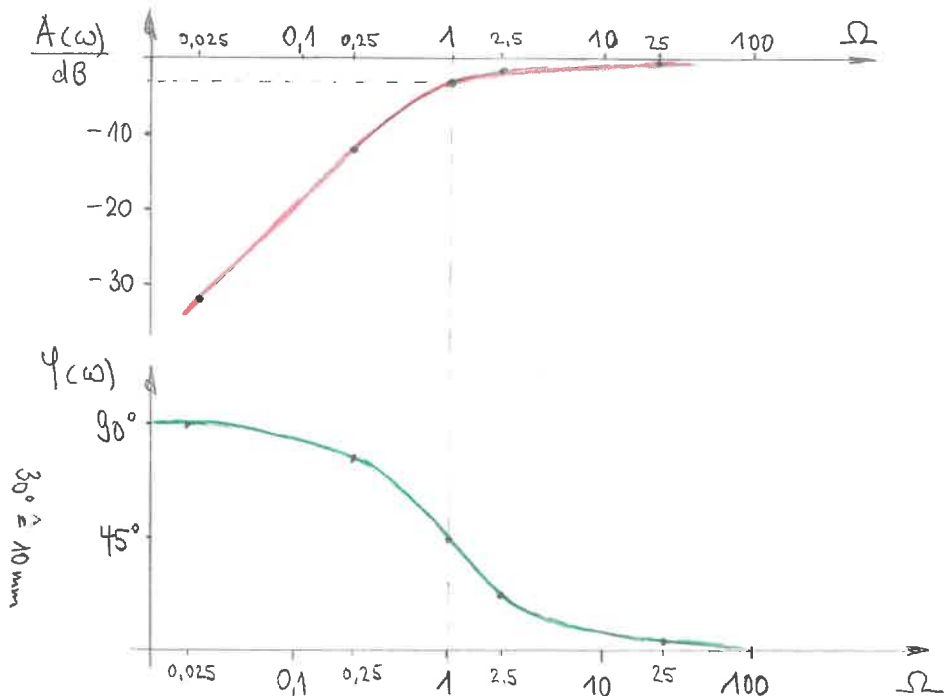
Darstellung des Amplitudenganges:

$$\frac{A(\omega)}{\text{dB}} = 20 \cdot \lg \frac{U_2}{U_1}$$

für Hochpass gilt:
 $\varphi(\omega) = \arctan \frac{\omega_g}{\omega}$

$$\varphi(\omega) = \arctan \frac{1}{\Omega}$$

f in Hz	ω in s^{-1}	$\Omega = \frac{\omega}{\omega_g}$	$\frac{U_2}{U_1}$	A(ω)	$\varphi(\omega)$
10	62,83	0,025	0,025	-32 dB	88,6°
100	628,3	0,25	0,25	-12 dB	75,9°
400	2.513	0,995	0,705	-3 dB	45°
1.000	6.283	2,488	0,928	-0,65 dB	21,9°
10.000	62.832	24,88	0,999	-0,007 dB	2,3°



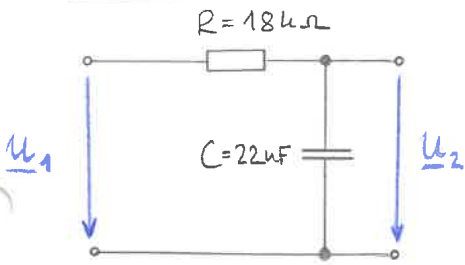
30° ≈ 10 mm

8. AC-Technik (Frequenzverhalten) - Teil 2

8.5) Aufg.: RC-Tiefpass ; $f_n = 10 \text{ Hz}, 100 \text{ Hz}, 400 \text{ Hz}, 1 \text{ kHz}, 10 \text{ kHz}$;
 $R = 18 \text{ k}\Omega$ u. $C = 22 \mu\text{F}$

Ges.: Amplituden- u. Phasengang für die Frequenzen f_n

Lös.:



$$\frac{U_2}{U_1} = \frac{1}{\frac{1}{j\omega C} + R} = \frac{1}{1 + j\omega RC}$$

$$\frac{U_2}{U_1} = \frac{1}{\sqrt{1 + (\omega RC)^2}}$$

- 3 dB - Grenzfrequenz:

$$\omega_g = \frac{1}{R \cdot C} \rightarrow f_g = \frac{1}{2\pi \cdot R \cdot C}$$

normierte Frequenz:

$$\Omega = \frac{\omega}{\omega_g} = \frac{\omega}{\frac{1}{RC}} = \omega RC$$

$$\omega_g = \frac{1}{RC} =$$

Darstellung des Amplitudenganges:

$$\frac{A(\omega)}{\text{dB}} = 20 \cdot \lg \frac{U_2}{U_1}$$

$$= \frac{1}{18 \cdot 10^3 \frac{\text{V}}{\text{A}} \cdot 22 \cdot 10^{-6} \frac{\text{As}}{\text{V}}} =$$

$$= 2.525,25 \frac{1}{\text{s}}$$

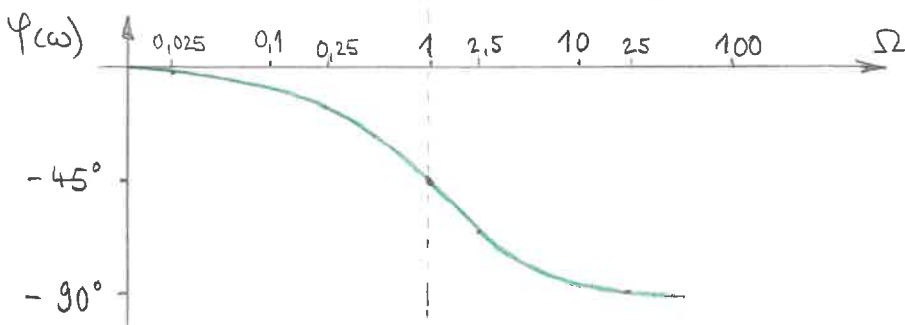
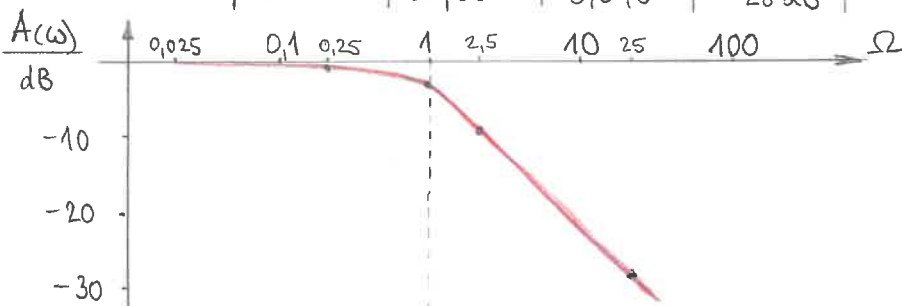
$$(f_g = 401,9 \text{ Hz})$$

für Tiefpass gilt:

$$\varphi(\omega) = -\arctan \frac{\omega}{\omega_g}$$

$$\rightarrow \varphi(\omega) = -\arctan \Omega$$

f in Hz	ω in s^{-1}	$\Omega = \frac{\omega}{\omega_g}$	$\frac{U_2}{U_1}$	$A(\omega)$	$\varphi(\omega)$
10	62,83	0,025	0,999	-0,003 dB	-1,4°
100	628,3	0,25	0,970	-0,26 dB	-14°
400	2.513	0,995	0,709	-3 dB	-45°
1.000	6.283	2,488	0,373	-9 dB	-68°
10.000	62.832	24,88	0,040	-28 dB	-88°



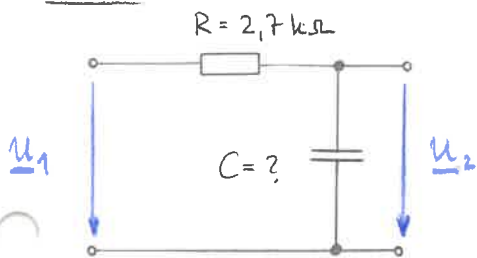
8. AC-Technik (Frequenzverhalten) - Teil 2

8.6) Ges.: bei $f = 1,8 \text{ kHz}$ Dämpfung 20 dB ; $R = 2,7 \text{ k}\Omega$;

Ges.: a) $C = ?$; b) ω_g u. f_g ? , c) $L = ?$

d) Amplituden- u. Phasengang

Lös.:



$$a) \frac{u_2}{u_1} = \frac{\frac{1}{j\omega C}}{\frac{1}{j\omega C} + R} = \frac{1}{1 + j\omega RC}$$

$$\frac{u_2}{u_1} = \frac{1}{\sqrt{1 + (\omega RC)^2}}$$

$$-20 \text{ dB} = 20 \cdot \lg \frac{u_2}{u_1}$$

$$-1 = \lg \frac{u_2}{u_1} \rightarrow \frac{u_2}{u_1} = 10^{-1} = 0,1 ;$$

$$0,1 = \frac{1}{\sqrt{1 + (\omega RC)^2}}$$

$$1 + (\omega RC)^2 = 100 \rightarrow (\omega RC)^2 = 99$$

$$C = \frac{\sqrt{99}}{2\pi \cdot f \cdot R} = \frac{\sqrt{99}}{2\pi \cdot 1,8 \cdot 10^3 \frac{1}{s} \cdot 2,7 \cdot 10^3 \frac{V}{A}} = \underline{\underline{325,8 \mu F}}$$

$$b) \frac{u_2}{u_1} = \frac{1}{\sqrt{2}} = \frac{1}{\sqrt{1 + (\omega RC)^2}}$$

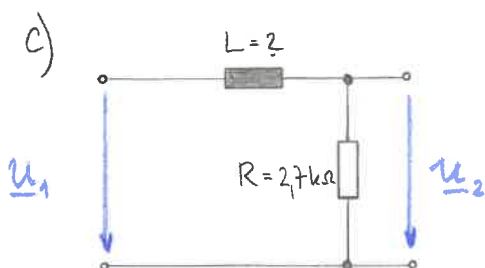
$$\rightarrow 1 = \frac{2}{1 + (\omega_g \cdot R \cdot C)^2}$$

$$1 + (\omega_g \cdot R \cdot C)^2 = 2$$

$$\omega_g \cdot R \cdot C = 1$$

$$\rightarrow \omega_g = \frac{1}{RC} = \frac{1}{2,7 \cdot 10^3 \frac{V}{A} \cdot 325,8 \cdot 10^{-9} \frac{As}{V}} = \underline{\underline{1.136,8 \frac{1}{s}}}$$

$$f_g = \frac{\omega_g}{2\pi} = \frac{1.136,8 \frac{1}{s}}{2\pi} = \underline{\underline{180,9 \text{ Hz}}}$$



$$\frac{u_2}{u_1} = \frac{R}{R + j\omega L} = \frac{1}{1 + j\frac{\omega L}{R}}$$

$$\frac{u_2}{u_1} = \frac{1}{\sqrt{1 + (\frac{\omega L}{R})^2}} ; \frac{u_2}{u_1} = \frac{1}{\sqrt{2}}$$

$$\Rightarrow 1 = \frac{2}{1 + (\frac{\omega_g \cdot L}{R})^2} \rightarrow 1 + (\frac{\omega_g \cdot L}{R})^2 = 2 \rightarrow \omega_g = \frac{R}{L} \text{ bzw. } \underline{\underline{L = \frac{R}{\omega_g} = \frac{2,7 \cdot 10^3 \frac{V}{A}}{1.136,8 \frac{1}{s}} = 2,38 \frac{Vs}{A} = 2,38 \text{ H}}}$$

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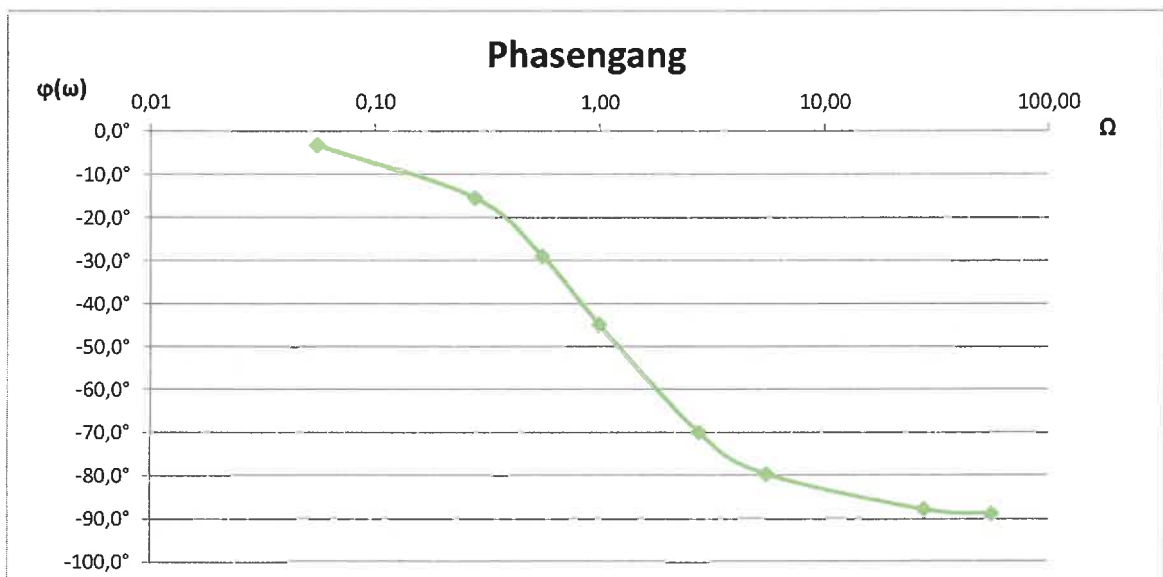
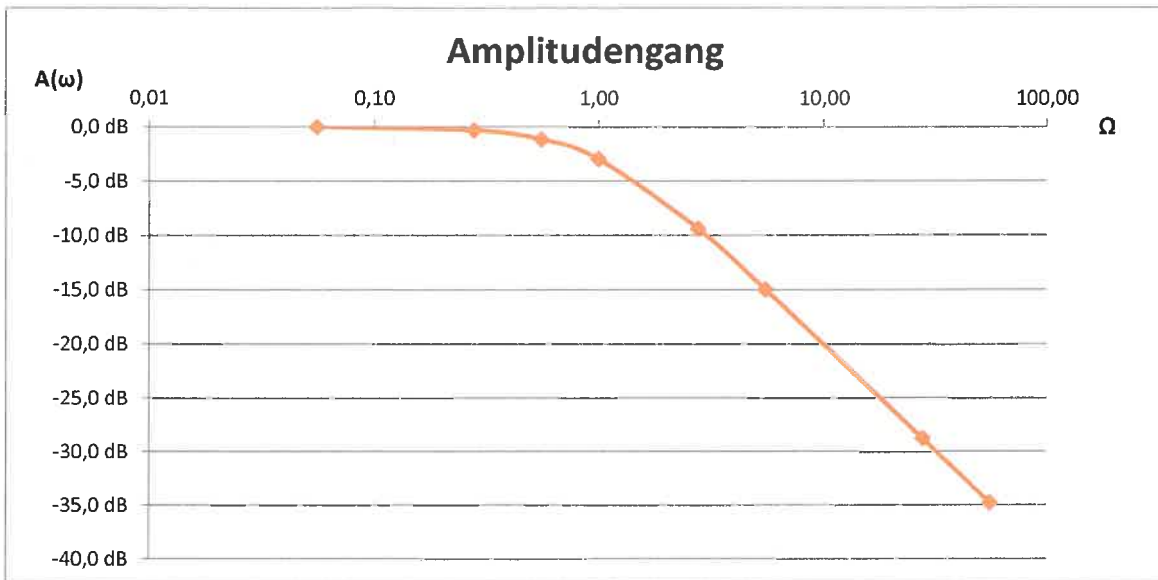
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Aufg. 8.6: RC-Tiefpass

f in Hz	ω in s^{-1}	$\Omega = \omega/\omega_g$	U_2/U_1	A(ω)	$\varphi(\omega)$	C= 325,84 nF
10 Hz	62,83	0,055	0,998	-0,013 dB	-3,2°	
50 Hz	314,16	0,276	0,964	-0,320 dB	-15,4°	
100 Hz	628,32	0,553	0,875	-1,158 dB	-28,9°	
180 Hz	1.130,97	0,995	0,709	-2,988 dB	-44,9°	
500 Hz	3.141,59	2,764	0,340	-9,364 dB	-70,1°	
1.000 Hz	6.283,19	5,527	0,178	-14,990 dB	-79,7°	
5.000 Hz	31.415,93	27,635	0,036	-28,835 dB	-87,9°	
10.000 Hz	62.831,85	55,271	0,018	-34,851 dB	-89,0°	

Aufg. 8.6: RL-Tiefpass

f in Hz	ω in s^{-1}	$\Omega = \omega/\omega_g$	U_2/U_1	A(ω)	$\varphi(\omega)$	L= 2,375 H
10 Hz	62,83	0,055	0,998	-0,013 dB	-3,2°	
50 Hz	314,16	0,277	0,964	-0,321 dB	-15,5°	
100 Hz	628,32	0,554	0,875	-1,162 dB	-29,0°	
180 Hz	1.130,97	0,997	0,708	-2,997 dB	-44,9°	
500 Hz	3.141,59	2,769	0,340	-9,380 dB	-70,1°	
1.000 Hz	6.283,19	5,539	0,178	-15,007 dB	-79,8°	
5.000 Hz	31.415,93	27,693	0,036	-28,853 dB	-87,9°	
10.000 Hz	62.831,85	55,385	0,018	-34,869 dB	-89,0°	



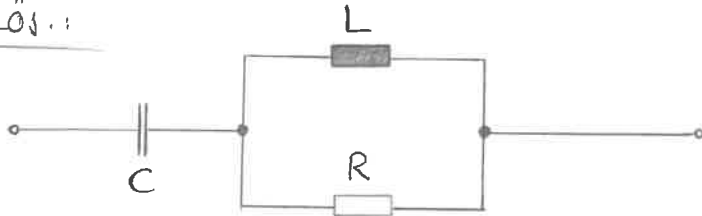
8. AC-Technik (Frequenzverhalten) - Teil 2

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8.7) Geg.: $C = 1,25 \mu\text{F}$; $L = 10 \text{ mH}$; $R = 125 \Omega$;

Ges.: Resonanzfrequenz $f_0 = ?$

Lös.:



$$X_C = \frac{1}{j\omega C} ;$$

$$X_L = j\omega L$$

$$\underline{Z} = -jX_C + \frac{jX_L \cdot R}{jX_L + R}$$

$$\underline{Z} = -jX_C + \frac{jX_L \cdot R \cdot (R - jX_L)}{(R + jX_L) \cdot (R - jX_L)} = -jX_C + \frac{jX_L \cdot R^2 + X_L^2 \cdot R}{R^2 + X_L^2}$$

$$\underline{Z} = \frac{-jX_C \cdot (R^2 + X_L^2) + jX_L \cdot R^2 + X_L^2 \cdot R}{R^2 + X_L^2}$$

$$\underline{Z} = \underbrace{\frac{X_L^2 \cdot R}{R^2 + X_L^2}}_{\text{Re}\{\underline{Z}\}} + j \underbrace{\frac{X_L \cdot R^2 - X_C \cdot R^2 - X_C \cdot X_L^2}{R^2 + X_L^2}}_{\text{Im}\{\underline{Z}\}}$$

$$\text{Im}\{\underline{Z}\} = 0 = \frac{X_L \cdot R^2 - X_C \cdot R^2 - X_C \cdot X_L^2}{R^2 + X_L^2}$$

$$\rightarrow 0 = X_L \cdot R^2 - X_C \cdot R^2 - X_C \cdot X_L^2$$

$$0 = 2 \cdot \pi \cdot f_0 \cdot L \cdot R^2 - \frac{R^2}{2 \cdot \pi \cdot f_0 \cdot C} - \frac{(2 \cdot \pi \cdot f_0 \cdot L)^2}{2 \cdot \pi \cdot f_0 \cdot C}$$

$$0 = \frac{(2 \cdot \pi \cdot f_0)^2 \cdot L \cdot C \cdot R^2 - R^2 - (2 \cdot \pi \cdot f_0 \cdot L)^2}{2 \cdot \pi \cdot f_0 \cdot C}$$

8. AC-Technik (Frequenzverhalten) - Teil 2

8.7) $0 = \frac{(2\pi \cdot f_0)^2 \cdot L \cdot C \cdot R^2 - (2\pi \cdot f_0 \cdot L)^2 - R^2}{2\pi \cdot f_0 \cdot C}$ ← Zähler = 0!

$$0 = f_0^2 \cdot (4\pi^2 \cdot L \cdot C \cdot R^2 - 4\pi^2 \cdot L^2) - R^2$$

$$f_0^2 = \frac{R^2}{4\pi^2 \cdot L \cdot C \cdot R^2 - 4\pi^2 \cdot L^2}$$

$$f_0 = \frac{R}{\sqrt{4\pi^2 \cdot L \cdot C \cdot R^2 - 4\pi^2 \cdot L^2}} = \frac{R}{2\pi \cdot \sqrt{L \cdot C \cdot R^2 - L^2}}$$

$C = 1,25 \mu F = 1,25 \cdot 10^{-6} \frac{As}{V}$; $L = 10 \text{ mH} = 10 \cdot 10^{-3} \frac{Vs}{A}$; $R = 125 \frac{V}{A}$;

$$f_0 = \frac{125 \frac{V}{A}}{2\pi \cdot \sqrt{10 \cdot 10^{-3} \frac{Vs}{A} \cdot 1,25 \cdot 10^{-6} \frac{As}{V} \cdot (125 \frac{V}{A})^2 - (10 \cdot 10^{-3} \frac{Vs}{A})^2}} = 2,038 \cdot 10^3 \frac{1}{s} = 2.038 \text{ Hz}$$